

Wireless LAN with focus on IEEE 802.11 and 802.11e

Slides contributed by

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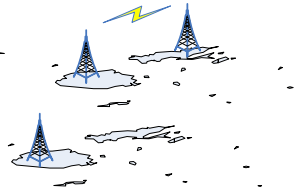
Lecture outline

- ▶ A short history of the WLAN development
 - ▶ IEEE 802.11 with focus on the MAC layer
 - ▶ Some performance issues related to 802.11
 - ▶ IEEE 802.11e
 - ▶ A brief overview of HiperLAN Type 1
 - ▶ Some facts about HiperLAN Type 2
-

A Short History...

▶ Classical Aloha

- ▶ University of Hawaii (ALOHANET) in 1970, interconnect the islands
- ▶ Packet radio com. cf. ARPANET
- ▶ No central control, packets arrived randomly in time
- ▶ Max channel utilization of 0.18 was achieved
- ▶ Simultaneous transmission resulted in collisions



▶ Slotted Aloha

- ▶ Senders synchronized and transmissions started at slot boundaries, random backoff
- ▶ Increased capacity to 0.37

▶ Carrier Sense Multiple Access (CSMA)

- ▶ "Listen before sending scheme", send if channel idle
- ▶ *non-persistent*: sends immediately and if busy waits a random time until retry
- ▶ *p-persistent*: transmits with prob p if medium idle and defers next slot with $1-p$
- ▶ *CSMA/CA*: backoff, carrier sensing to achieve fairness

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A Short History...

▶ HiperLAN Type 1

- ▶ Published in 1996 by ETSI, No commercial success.
- ▶ *EY-NPMA* (Elimination Yield Non-Preemptive Multiple Access)
- ▶ Nodes transmits bursts of different lengths (Geometric distribution)
- ▶ Efficient protocol, small prob. of collisions, supports some QoS

▶ IEEE 802.11

- ▶ Uses CSMA/CA, standard first published in 1997 by IEEE, no QoS
- ▶ Commercial success, most widely deployed WLAN standard
- ▶ Little competition from other technologies

▶ HiperLAN Type 2

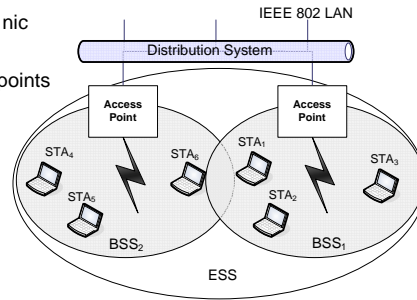
- ▶ Published in 2000 by ETSI, quite unlike HiperLAN Type 1
- ▶ Complex standard, TDMA/TDD scheme, central control, supports QoS
- ▶ No products available only prototypes, uncertain future

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Components and Architecture of 802.11

The 802.11 standard defines the following components

- **Station (STA)**
 - A mobile node, e.g. Laptop with WLAN nic
- **Access Point (AP)**
 - STAs connected/associated to access points
- **Basic Service Set (BSS)**
 - Access Point and mobile STAs
- **Basic Service Area (BSA)**
 - Geographical area covered by a BSS
- **Extended Service Set (ESS)**
 - A set of BSSs joined together
- **Distribution System (DS)**
 - Interconnects multiple BSS, backbone network, e.g. Ethernet IEEE 802.3

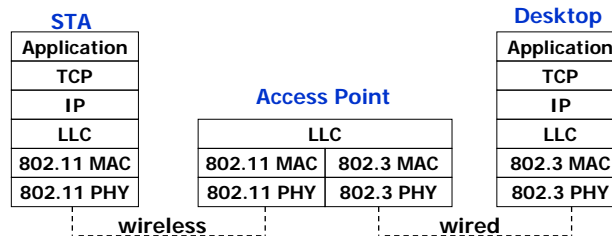


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802.11 Protocol Architecture

▶ 802.11 Layers defined

- ▶ PHY Layer (Physical Layer) - Many different technologies
- ▶ MAC Layer (Medium Access) - Only one MAC technology so far...
- ▶ LLC (Logical Link Control) - a logical interface to higher layers



- ▶ The AP only works as a bridge

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802.11 Physical Layer

- ▶ **3 PHY layers defined in original 802.11 (1997)**
 - ▶ **Frequency Hopping Spread Spectrum (FHSS)**
 - Operating in 2,4 GHz, ISM band, no license required
 - Frequency hopping, similar to Bluetooth, rates up to 2 Mbps
 - ▶ **Direct Sequence Spread Spectrum (DSSS)**
 - Operating in 2,4 GHz band, ISM band
 - The signal is spread over a wider spectrum, rates up to 2 Mbps
 - ▶ **Infrared**
 - limited use...Short range, typically 10 meters, rates up to 2 Mbps
- ▶ **Several new PHY layers have been standardized**
 - But the MAC layer remains the same as in the first standard

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802.11: Physical layer extensions

- ▶ **IEEE 802.11b**
 - ▶ Standardized in 1999, High Rate DSSS, CCK modulation
 - Spread Spectrum tech., chip rate 11 MHz, barker sequence, ISM band
 - ▶ Two different PHY header formats
 - Backward compatibility to previous DSSS
 - Less overhead (short preamble)
 - ▶ Supports rate: 5.5, 11 Mbps
 - Also supports the lower rates 1 and 2 Mbps (DBPSK, DQPSK)
 - Almost all products supports 802.11b
 - ▶ Subdivides the ISM band into
 - 13 overlapping channels or 3 non-overlapping channel

<http://standards.ieee.org/getieee802/download/802.11b-1999.pdf>

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802.11: Physical layer extensions

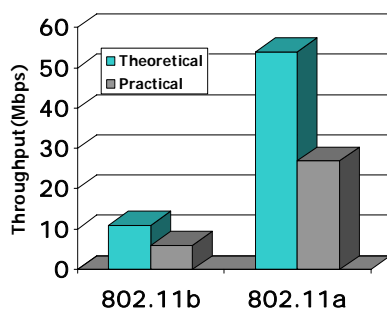
▶ IEEE 802.11a

- ▶ Standardized in 1999, Multi carrier modulation
- ▶ OFDM (Orthogonal Frequency Division Multiplexing)
 - Bit stream is split into several low bit streams
 - Each bit stream uses a different carrier, 52 sub-carriers
- ▶ Supports rates: 6,9,12,18,24,36,48,54 Mbps
 - BPSK,QPSK,QAM: Different number of bits/symbol
- ▶ Uses the 5GHz band
 - Regulatory issues (not license free band in many European countries)
 - DFS and TPS may be required
 - Only Indoor use in Sweden, max power 200mW EIRP (5150-5250 MHz)
 - Hard to find the exact regulations in the band, PTS only gives little info

<http://standards.ieee.org/getieee802/download/802.11a-1999.pdf>

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802.11a and b Throughput performance



Note: This result is for a single user

▶ Large protocol overhead

- ▶ Inefficient design of the MAC
- ▶ and PHY layers limits the throughput

▶ Work is ongoing (11n)

- ▶ To overcome these limitations
- ▶ Achieve at least 100 Mbps at MAC

▶ If considering more STAs

- ▶ Contention for the medium will arise resulting in an additional overhead

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802.11 Medium Access Control

▶ MAC responsibilities

- I. Controlling Access to Medium
- II. Reliable data delivery
- III. Fragmentation of frames
- IV. Roaming & authentication
- V. Power Save functionality

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802.11 MAC Mechanisms

▶ Access Mechanisms used by MAC

- ▶ **CSMA/CA**
 - The MAC algorithm used to access the medium
- ▶ **Binary exponential backoff (BEB)**
 - Used to decrease the contention for the medium
- ▶ **Carrier Sensing**
 - Used to determine if medium is idle or busy

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802.11 Carrier Sensing

▶ Physical carrier sense

- Senses the medium to determine if channel is idle
- Based on CCA (Clear Channel Assessment)
- Works by detecting a energy level of the channel
- A interference strength above *the carrier sense threshold* -> busy
- The implementation of CCA is PHY layer dependent

▶ Virtual carrier sense

- Every STA keeps a Network Allocation Vector (NAV)
- NAV tells the STA when medium is busy
- NAV is updated by a field in the MAC frame of every packet heard
- NAV has precedence over physical carrier sense

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802.11 CSMA/CA

▶ CSMA/CA (Collision Avoidance)

- ▶ Carrier Sense Multiple Access with Collision Avoidance
- ▶ For wireless communication
- ▶ Collision avoidance before transmission
- ▶ CS is used to determine if medium is idle before sending data

▶ CSMA/CD (Collision Detection)

- ▶ Carrier Sense Multiple Access with Collision Detection
- ▶ Used in wired Ethernet, IEEE 802.3
- ▶ A collision is detected while transmitting
- ▶ Sender aborts the transmission if collision is detected

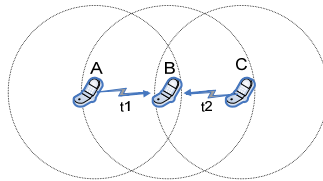
Why is collision avoidance used in wireless and not collision detection?

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802.11 CSMA/CA

▶ Collision detection not feasible in Wireless LANs

- ▶ The collision happens at the receiver side
 - Strong attenuation cf. wired networks



1. A and C out of range
 2. A starts transmitting at t_1
 3. C senses medium idle and starts transmitting at t_2
 4. Collision happens at B
- A and C do not know about the collision
A is called a "hidden terminal" with respect to C and vice versa

- ▶ Radio architecture
 - Switching between receive and transmit (Half Duplex) , Only one antenna
- ▶ Difference in energy/power for transmit and receive
 - Transmit power \gg receive power (million times), difficult to detect difference

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802.11: Physical Carrier Sense threshold

▶ The Physical Carrier Sense Threshold

- ▶ Translates to a detection range (R_{cs})
- ▶ Usually larger than the transmission range (R_{tx})

▶ Size of the CS threshold

▶ Increased Threshold

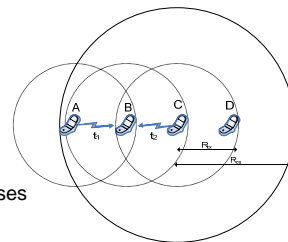
- The detection range increases.
- HT problem decreases and ET problem increases
- Spatial reuse of the channel decreases

▶ Decreased Threshold

- The detection range shrinks
- ET problem decreases and HT problem increases
- Spatial reuse of the channel increases

▶ The CS threshold has a large effect

- ▶ The HT and ET problems and the spatial reuse of the channel
- ▶ -> Capacity of the whole system



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Binary Exponential Backoff (BEB)

- ▶ **802.11 Backoff has mainly two purposes**
 - ▶ Adjust the contention level under various traffic loads
 - ▶ Provide some degree of fairness among STAs
- ▶ **Backoff Counter**
 - ▶ Determines time to wait before a transmission attempt
 - ▶ Uniformly chosen within CW
 - ▶ Only decremented when medium is idle
 - ▶ Packet sent when counter reaches zero
- ▶ **Contention Window (CW)**
 - ▶ Upper and lower bound on the backoff counter
 - ▶ CW is doubled for every collision or lost frame

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802.11 Binary Exponential Backoff

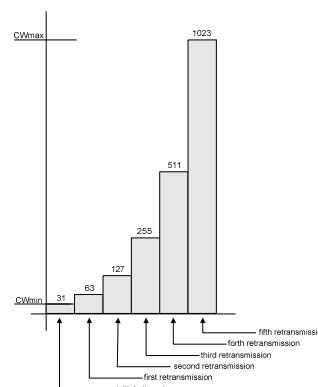
- ▶ **Binary Exponential Backoff definition**

$$BO \in U\{0, CW\}$$

$$CW \in [CW_{min}, CW_{max}]$$

- ▶ **Uniform distribution**
- ▶ **Backoff performed per packet basis**
- ▶ **Pre and post backoff**
- ▶ **CW parameters are PHY dependent**

802.11b: $CW_{min} = 31$ $CW_{max} = 1023$
 802.11a: $CW_{min} = 15$ $CW_{max} = 1023$



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802.11: Binary Exponential Backoff

▶ Example of CW adjustment

Attempt	Contention Window	Size	ACK
1	$CW = CW_{min}$	$2^5 - 1 = 31$	NO
2	$CW = (CW + 1)2 - 1$	$2^6 - 1 = 63$	NO
:	:	:	NO
n	$CW = \min(CW_{max}, (CW + 1)2 - 1)$	$\min(1023, 2^n - 1)$	YES
1	$CW = CW_{min}$	$2^5 - 1 = 31$	YES
1	$CW = CW_{min}$	$2^5 - 1 = 31$	YES

▶ Two additional parameters affecting the CW

- ▶ Maximum number of transmission attempts for
 - Data packets is called **Short Retry Limit**, default value is 4
 - Control packets is **Long Retry Limit**, default value is 7
- ▶ Interestingly, the SRL prevents CW from reaching CW_{max}

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802.11: Stop and Wait ARQ

■ Automatic Repeat Request (ARQ)

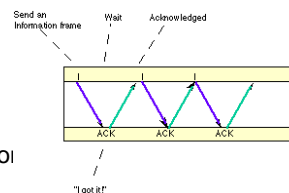
- Error control
- and flow control mechanism

■ Stop and Wait ARQ protocol

- Each packet reception confirmed with an ACK frame
- Serves 2 purposes: detect lost packets and adjust the CW

■ Large overhead in ARQ

- Sliding window protocols
 - **Go-back-N**
 - **Selective Repeat**
- More suitable for continuous transmission
- 802.11e option for Selective Repeat



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802.11 Medium Access Methods

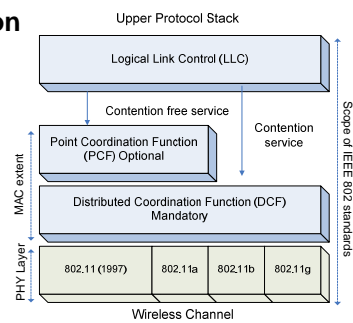
Two methods to access the wireless medium exist

- ▶ **Distributed Coordination Function**

- ▶ (DCF), Distributed algorithm
- ▶ STAs contend for access
- ▶ *Mandatory* in standard

- ▶ **Point Coordination Function**

- ▶ (PCF), Centralized algorithm
- ▶ AP is controlling access
- ▶ Builds upon the mandatory DCF
- ▶ *Optional* in standard



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Medium Access Methods

- ▶ **Distributed Coordination Function (DCF)**

- ▶ **Physical** and **Virtual** carrier sense (NAV) is used
- ▶ **CSMA/CA**, STAs contend for access to the channel
- ▶ **ARQ**: ACK required for each successful transmission
 - ACK Timeout -> lost packet
- ▶ **Backoff** is used if medium is busy or frame is lost
- ▶ Medium Reservation with **RTS/CTS**
 - Avoid collisions (hidden terminal problem)

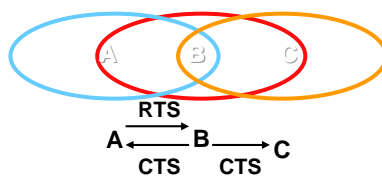
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RTS/CTS handshake

▶ Request to Send/Clear to Send (RTS/CTS)

1. The source issues a Request to Send (RTS) packet
2. The destination responds with a Clear to Send (RTS) packet
3. Source starts transmitting the data
4. Destination responds with an ACK

▶ All STA hearing this "handshake" will know about the coming transmission and defer access



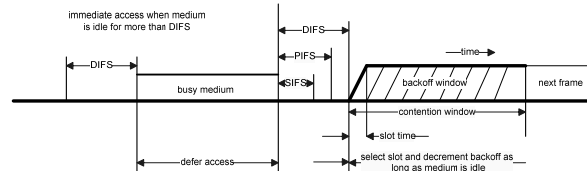
- A and C want to send to B
- A sends RTS to B
- B sends CTS to A
- C "overhears" CTS from B
- C waits for duration of A's transmission

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Inter Frame Spaces (IFS)

▶ Transmissions are separated by short Inter Frame Spaces

- ▶ Used for priority access to the medium
- ▶ Short IFS (*SIFS*), Point Coordination Function IFS (*PIFS*) and
- ▶ Distributed Coordination Function IFS (*DIFS*)

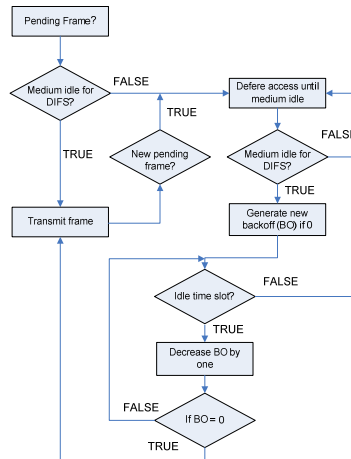


▶ Extended Inter Frame Space (EIFS)

- ▶ STAs receiving a corrupted frame (and is not the receiver) should defer access when medium becomes idle again for a EIFS (approx the time to transmit an ACK)
- ▶ Purpose is to provide enough time for the receiver (if correctly received the frame) to respond with an ACK frame

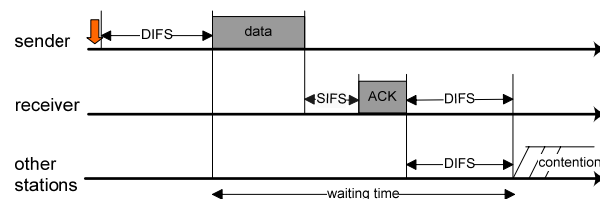
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DCF Basic Access Method



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DCF Basic Access Method

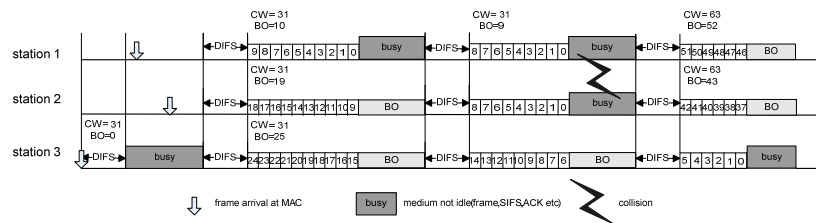


Backoff counter is decremented by one for every slot time medium is detected idle (after first waiting a DIFS)

↓ Packet arrives at MAC layer

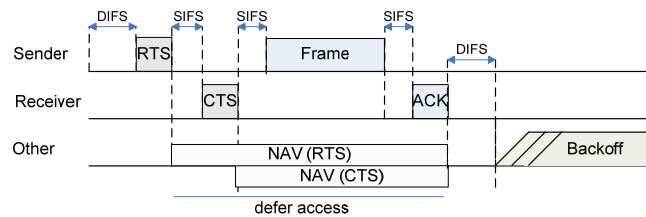
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DCF Contention with collision



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DCF Access using RTS/CTS



- ▶ The RTS/CTS packet contains the duration of the transmission
- ▶ STAs hearing the RTS/CTS packet updates its NAV accordingly
 - ▶ This is virtual carrier sensing
- ▶ RTS/CTS imposes an additional overhead
 - ▶ Overhead is larger for small packets, a RTS/CTS threshold is used

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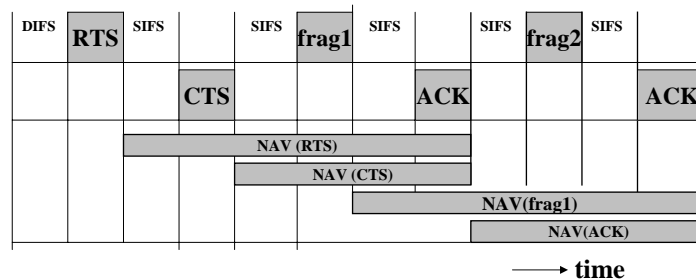
Fragmentation

- ▶ **Wireless LANs experience high bit error rates**
 - ▶ Error rates in WLANs >> LANs, Medium experience error bursts
- ▶ **Smaller probability of error with shorter frames**
 - ▶ Smaller frames have better chance of escaping error burst
 - ▶ Fragmentation may be a way to increase throughput
 - ▶ Increased overhead, more header information/per data unit
- ▶ **Fragmentation threshold**
 - ▶ Only packets above a threshold is fragmented, Manually configured

The probability that a frame arrives without error P_1 assuming the bit errors P_b are independent and constant is $P_1 = (1 - P_b)^N$, where N is the number of bits per frame

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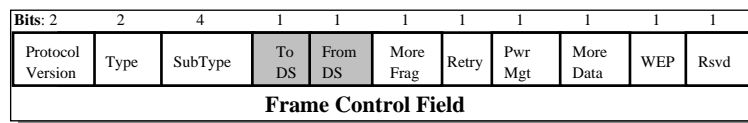
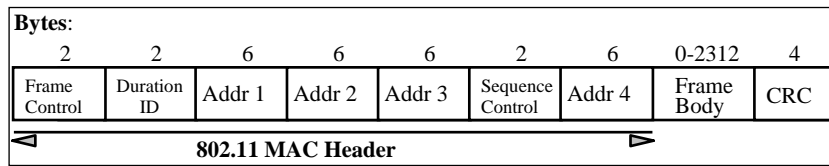
Fragmentation burst



- ▶ If one fragment is lost backoff procedure is invoked
- ▶ Fragmentation may also be used without RTS/CTS

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802.11 MAC Frame



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802.11 MAC Management

- ▶ **Synchronization**
 - ▶ STAs need to be synchronized with the WLAN (on the MAC layer)
 - ▶ In Infrastructured mode, STA synchronized with AP
 - ▶ Necessary for Power management and PCF operation
- ▶ **Power Management**
 - ▶ STAs may have limited battery capacity
 - ▶ Power Save features necessary, sleep mode
- ▶ **Roaming**
 - ▶ Terminals may enter a new BSS
 - ▶ Terminal must change AP
 - ▶ Like Handover in GSM (but not as smooth)
- ▶ **Authentication & encryption**
 - ▶ Authentication before access to the network
 - ▶ Encryption of data to prevent eavesdrop

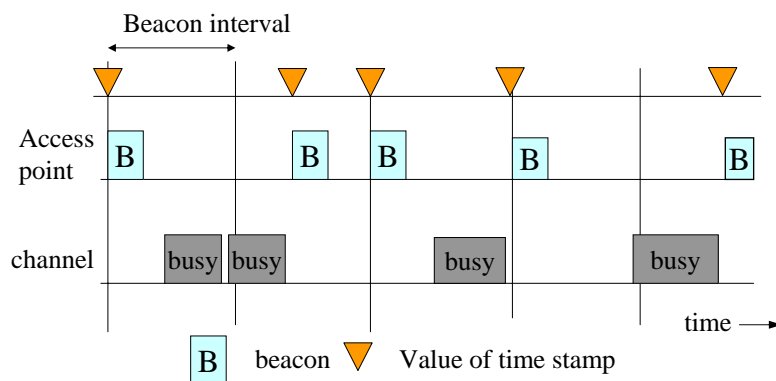
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Synchronization

- ▶ **All STA timers in a BSS are synchronized**
 - ▶ Needed for Power management and
 - ▶ PCF coordination
- ▶ **The access point maintains a clock**
 - ▶ The AP transmits periodic frames called *Beacons*
 - ▶ The Beacon contains the clock value
 - ▶ Time between two beacons are called the *beacon interval*
- ▶ **STAs hearing the beacon updates their clock**
 - ▶ This prevents clock drifting
- ▶ **The beacon is transmitted using normal CSMA/CA**
 - ▶ Beacon may be delayed significantly

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Synchronization (cont.)



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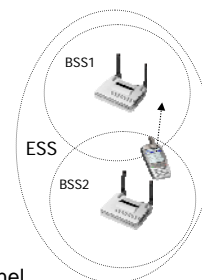
Power Management

- ▶ **Purpose is to save battery capacity**
 - ▶ Limited battery capacity and 802.11 drains batteries fast!
 - ▶ Cisco Aironet: Tx 530-560 mA, Rx 280-330 mA, Standby 200 mA
- ▶ **A STA may enter sleeping mode and turn off the radios**
 - ▶ This is notified to the AP (a bit in the MAC header is flipped)
 - ▶ The AP maintains a list of STAs in Power saving mode
 - ▶ Packets for a sleeping STA are buffered in the AP
 - ▶ Buffered packets are sent to the STAs at designated times
- ▶ **STA must wake up periodically to receive beacons**
 - ▶ Beacon contains a *traffic indication map*, info on buffered frames
- ▶ **STAs are required to stay awake to receive the buffered data**
 - ▶ STA sends a PS-poll frame to the AP and waits to receive the buffered data
 - ▶ In power save mode: the consumption can be reduced to 30 mA

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Roaming between access points

- ▶ If a Mobile STA moves beyond the coverage of the AP
 - ▶ but within range of another AP than (within the ESS only)
- ▶ Packet losses and incapability problems exist
 - ▶ IEEE 802.11f (Inter Access Point Protocol)
- ▶ STA decides that link to its current AP is poor
 - ▶ Radio link quality, e.g. SNR and BER, missed beacons etc
- ▶ STA uses scanning function to find another AP
 - ▶ **Active scanning**, STA sends a probe request on each channel
 - ▶ **Passive scanning**, STA listens for beacons on each channel
 - ▶ Station sends Re-association Request to new AP
- ▶ If Re-association Response is successful
 - ▶ STA has roamed to a new AP else STA scans for another AP



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Association & Authentication

▶ Authentication

- ▶ Shared key authentication, AP sends a challenge k
STA encrypts k with the pre-shared key in the reply.
- ▶ The WEP encryption is not secure...802.11i improves

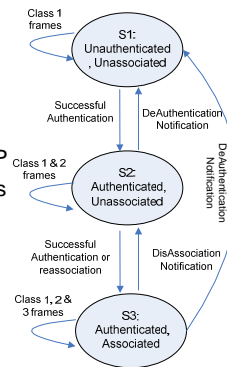
▶ Association

- ▶ STA needs to get synchronization information from AP
- ▶ Exchange capability information, e.g. Supported rates

▶ Disassociation

- ▶ May be performed by either STA or AP
- ▶ Data cannot be sent to a disassociated STA

Class 1: Control frames, e.g. ACK, RTS, (de) Authentication
Class 2: Management frames, e.g. (re) (dis) Association
Class 3: Data frames



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802.11 Link Adaptation (LA)

▶ Adjust the modulation scheme based on the link quality

- ▶ Improve the performance by minimizing packet loss
- ▶ Uses SNR/BER/ACK statistics to adjust the data rate
- ▶ Not defined in IEEE 802.11 but manufacturer dependant

▶ 11b four rates (1-11Mbps) and 11a eight (6-54Mbps)

- ▶ Every rate has a limited operating range
- ▶ Generally lower rates have larger operating ranges

▶ When a STA moves beyond the optimal range of a rate

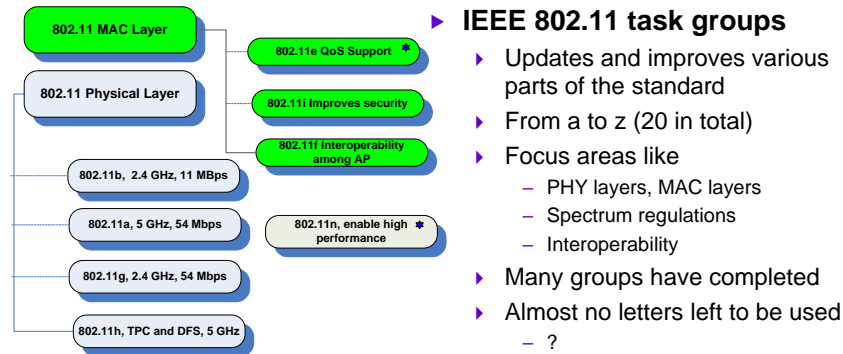
- ▶ the device will fall back to a lower rate
- ▶ The result is better performance, less packet errors

▶ However, LA may cause lower total system capacity!

- ▶ There is a performance anomaly using LA in a shared broadcast channel

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The 802.11 Alphabet Soup



Task group info and timeline: http://www.ieee802.org/11/802.11_Timelines.htm

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802.11: Contention window performance

- ▶ When considering a **fixed backoff scheme**. i.e. $CW_{\min} = CW_{\max}$
- ▶ The optimal CW under saturation is approximately

$$W^{opt} \approx n\sqrt{(2T)^*},$$

where T is the transmission time in *slotTimes*

- ▶ More complex relationship when considering a CW doubling scheme
 - But the dependency still remains to the number of users
- ▶ The biggest problem is how to approximate the optimal CW
 - The binary exponential backoff (BEB) scheme in 802.11 does a bad job
 - The BEB is discrete with little precision
- ▶ The CW is reset to CW_{\min} after each successful transmission
 - This may be non optimal under saturation

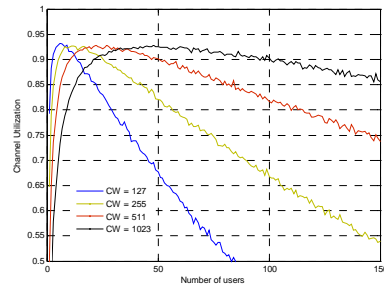
* G. Bianchi, Performance Analysis of the IEEE 802.11 DCF, IEEE Journal on Selected Areas in Communications, 18:3,2000

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Contention window performance

▶ A simple simulation of DCF

- ▶ 802.11a and fixed CW for an increasing number of STAs,
- ▶ Under saturation
- ▶ For a given number of STAs, **too small CW** yields many collisions
too large CW yields many idle slots
- ▶ Cost for a collision is high since the whole packet is transmitted
- ▶ ARQ is needed to detect the collisions
- ▶ Capacity is wasted



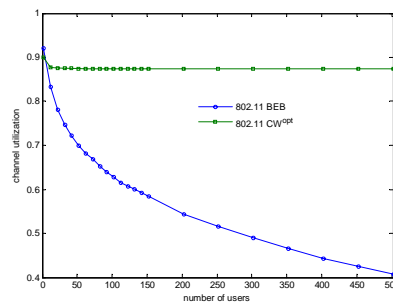
Number of users	Optimal CW
10	$CW^{opt} \approx 213$
20	$CW^{opt} \approx 426$
50	$CW^{opt} \approx 1065$
100	$CW^{opt} \approx 2132$
150	$CW^{opt} \approx 3204$

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Contention window performance

▶ A comparison between

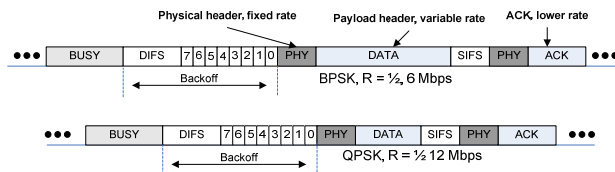
- ▶ 802.11 BEB (normal)
- ▶ 802.11 CW^{opt} , uses the optimal CW
- ▶ BEB used in 802.11 is far from optimal,
- ▶ especially for large number of users
- ▶ for few stations the result is satisfactory



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802.11: Theoretical throughput limit

- ▶ **Physical layer and MAC layer overhead**
 - ▶ A Theoretical throughput limit exists even if the data rate goes to infinity¹
 - ▶ Simply by increasing the rate without reducing the overhead is not an option
- ▶ **To achieve higher throughput, changes need to be done**
 - ▶ Task group n is working on both MAC and PHY enhancements to
 - ▶ achieve throughput figures above 100 Mbps
 - ▶ Frame aggregation: aggregate frames and thus reduce some overhead

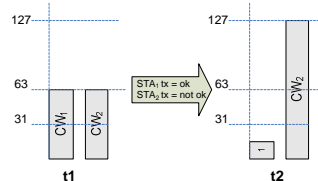
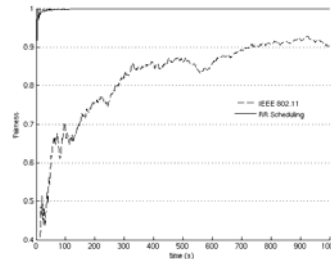


¹ Y. Xiao and R. Rosedahl, Throughput and Delay Limits of IEEE 802.11, IEEE Communications Letters, 6:8, 2002

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802.11 Fairness among Stations

- ▶ **Fairness has many definitions**
 - ▶ Generally how the capacity is shared
 - ▶ Fairness on different time scales
 - *Short* and *long* term fairness
 - ▶ 802.11 is not considered to be fair in the shorter time context
 - ▶ Fairness between STAs, EBB favors STAs that exceeded last and vice versa.
 - ▶ EIFS may also be a factor influencing Fairness



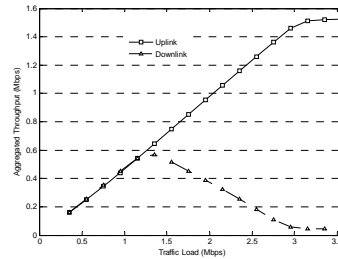
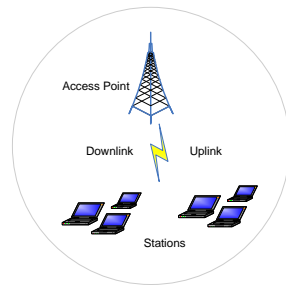
Min-max Fairness Index:

$$I_{min-max} = \frac{\min\{x_i\}}{\max\{x_j\}}$$
 where x is the rate or throughput.

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802.11 Uplink/downlink starvation

- ▶ AP has no precedence in medium access over STAs
- ▶ AP is responsible for all transmissions in the downlink



- ▶ The AP is easily starved by the uplink
- ▶ This problem has a large impact on TCP performance
- ▶ A fairness problem

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Definition of Quality of Service

- ▶ Applications have different QoS requirements
 - ▶ Real time Vs. non-real time applications
 - ▶ Streaming, Web browsing, email
- ▶ Elastic vs. Inelastic applications
 - ▶ Tolerance of variations in throughput
- ▶ Typical QoS parameters
 - ▶ Throughput, Delay, Jitter, Packet loss, Bit error rate
- ▶ Networks capable of satisfying requirements
 - ▶ Supports quality of service
 - ▶ Not all wireless networks implement QoS support
 - ▶ IEEE 802.11 DCF has not support

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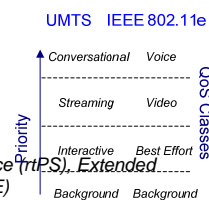
Motivation: QoS in wireless networks

- ▶ **QoS is not very prioritized in wired networks**
 - ▶ Implementing QoS is difficult! Adding more hardware is easy!
 - ▶ Capacity shortage is easily solved
- ▶ **Adding more hardware in wireless**
 - ▶ Is often not an option
 - ▶ Shannon's law, one ether shared by many, limited spectrum
- ▶ **Supporting QoS in wireless is important**
 - ▶ Limited resources, maximizing resource utilization important
 - ▶ Commercial interests, user satisfaction important
 - ▶ Operators want to maximize their revenue, support new services
- ▶ **QoS guarantees in wireless is difficult**
 - ▶ Too many uncertainty factors: interference, traffic load, handover
 - ▶ May be easier to provide QoS guarantees in wired networks

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Quality of Service Classes

- ▶ **Supporting arbitrary requirements is difficult**
 - ▶ One solution to this is *QoS classes*
 - ▶ Network optimizes performance according classes
 - ▶ An application belongs to a QoS class
- ▶ **Some networks utilizing QoS classes**
 - ▶ UMTS: *conversational, streaming, interactive, background*
 - ▶ IEEE 802.11e: *voice, video, Best effort, background*
 - ▶ WiMAX: *Unsolicited Grant Service (UGS), real-time Polling Service (rtPS), Extended rtPS (ertPS), Non-real-time polling service (nrtPS), Best effort (BE)*
- ▶ **Some service requirements**
 - ▶ Voice/speech: tolerates some losses sensitive to delay/jitter, delay in voice < 200ms
 - ▶ Streaming: tolerates some losses, less sensitive to delay/jitter
 - ▶ Data applications: generally more sensitive to losses than delay/jitter



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IEEE 802.11e (QoS support)

- ▶ **Defines the new Hybrid Coordination Function (HCF)**
 - ▶ Enhanced Distributed Channel Access (EDCA),
 - ▶ decentralized access
 - ▶ HCF Controlled Channel Access (HCCA),
 - ▶ centralized access
- ▶ **Some new mechanisms in 802.11e**
 - ▶ **User Priorities**, ranging from 0 to 7
 - ▶ **Access Categories (AC)**, four per STA
 - ▶ **Arbitration Inter Frame Space (AIFS)**
 - ▶ **Transmission opportunity (TXOP)**
 - ▶ **Block Acknowledgement**, more efficient ARQ scheme
 - ▶ **Admission Control**, increases control by AP

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802.11e: Priority mapping between UPs ACs.

Priority	User Priorities (UP)	Access Category (AC)	Designation
lowest	1	AC_BK	Background
	2	AC_BK	Background
:	0	AC_BE	Best Effort
	3	AC_BE	Best Effort
	4	AC_VI	Video
	5	AC_VI	Video
highest	6	AC_VO	Voice
	7	AC_VO	Voice

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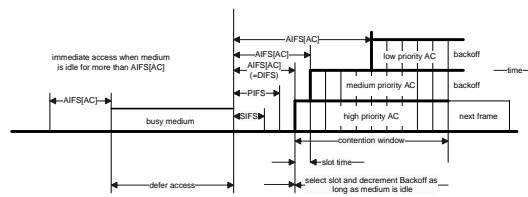
802.11e: Arbitration Inter Frame Space

▶ EDCA Parameters: AIFS (Arbitration Inter Frame Space)

- ▶ Time medium is sensed idle before an AC starts Tx or BO
- ▶ Not fixed as in DCF instead variable value, specific to the AC

$$AIFS = AIFSN \times SlotTime + SIFS$$

- ▶ Higher priority AC use smaller AIFSN
- ▶ Minimum allowed AIFSN is 2, which makes AIFS = DIFS

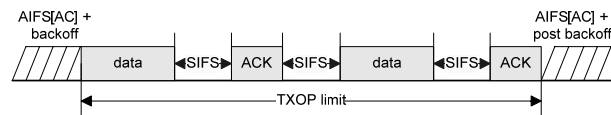


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802.11e: contention free bursting

▶ EDCA Parameters: Transmission Opportunity

- ▶ Each AC contends for a TXOP
- ▶ The *TXOP Limit* parameter defines its maximum length
- ▶ If length allows, multiple frames may be transmitted
- ▶ Consecutive transmissions are separated by SIFS
- ▶ This is called **Contention Free Bursting**



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802.11e: default contention parameters

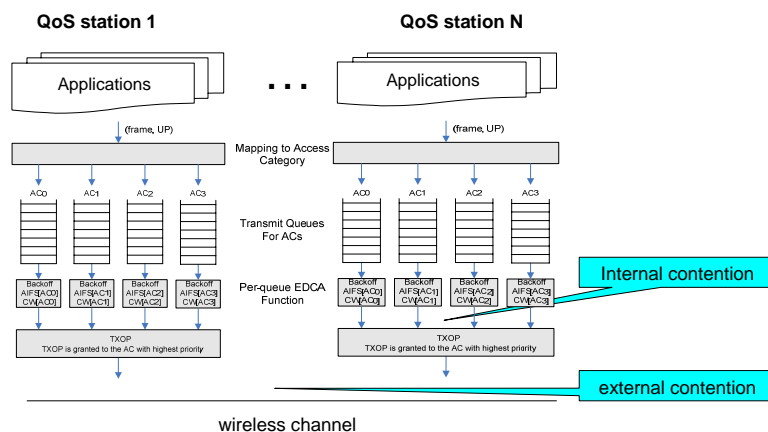
- ▶ AC Specific default contention parameters

AC	AIFSN	CW _{min}	CW _{max}
AC_VO	2	7	15
AC_VI	2	15	31
AC_BE	3	31	1023
AC_BK	7	31	1023

- ▶ These values are not fixed, can be dynamically adjusted by the AP
- ▶ No algorithm for doing so is given in the standard
- ▶ up to manufacturers

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802.11e EDCA: Basic concept

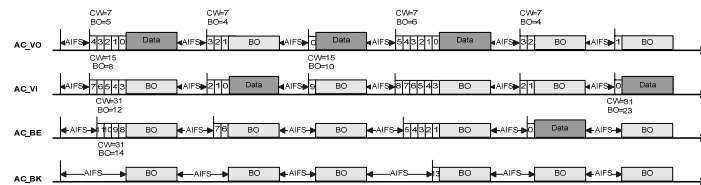


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802.11e: Internal contention

EDCA Access Mechanism

- ▶ Example: four EDCAFs contending *inside a single station*
- ▶ Each AC acts as a virtual station inside the station



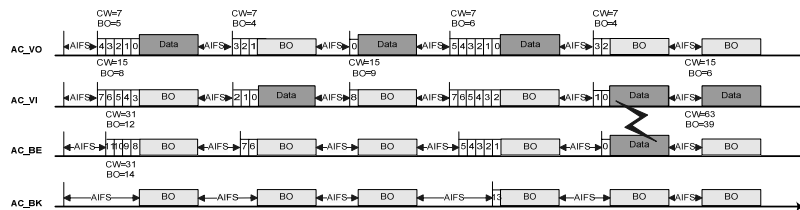
- ▶ Each AC contends independently from other ACs
- ▶ Each AC uses the specific CW values: CW[AC], AIFS[AC]

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802.11e: Internal contention

EDCA Access Mechanism

- ▶ Collisions among AC within a single STA, called Virtual Collisions

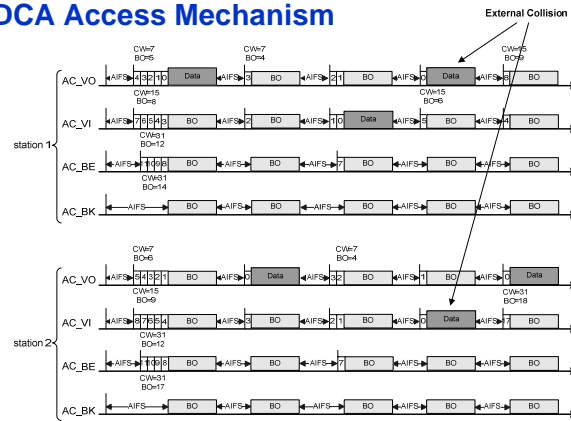


- ▶ **Virtual collisions:** solved by grating the highest AC access
- ▶ Other colliding ACs act as external collisions: doubling CW and backoff

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802.11e: external contention

▶ EDCA Access Mechanism



- ▶ Collisions among AC within a two STA may arise, real collisions

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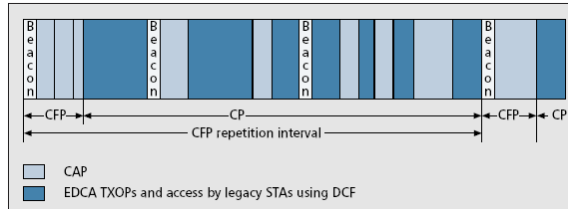
802.11e: HCF controlled channel access

- ▶ Similar to the legacy PCF, HCCA provides polled access to the wireless medium. In particular, HCCA uses a QoS-aware hybrid coordinator (HC), which is typically located at the QoS access point (QAP) in infrastructure WLANs.
- ▶ HC uses PIFS to gain control of the channel and then allocates TXOPs to QSTAs, which are referred as HCCA TXOPs or polled TXOPs.
- ▶ Unlike PCF, HCCA can poll the QSTAs during contention periods (CPs), and HCCA takes into account QSTAs' specific flow requirements in packet scheduling.
- ▶ Controlled access phase (CAP) is defined as the time period when HC maintains control of the medium.
- ▶ After grabbing the channel, the HC polls QSTAs in turn according to its polling list.
- ▶ In order to be included in the polling list of the HC, a QSTA must send a QoS reservation request using the special QoS management frame, and each individual flow needs one particular reservation request.

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802.11e: HCF controlled channel access

D. Gao et. Al. "Admission Control in IEEE802.11e Wireless LAN", IEEE Network, July/August, 2005



- ▶ CAP Controlled Access Phase
- ▶ CP Contention Period
- ▶ CFP Contention Free Period

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802.11e: Admission Control mechanism

- ▶ Gives the AP better control over the resource
 - ▶ Contention based Admission Control
 - ▶ Goal is to protect sensitive flows from ACs AC_VO and AC_VI
 - ▶ not to violate service commitments made earlier to granted flows
 - ▶ AP signals in the Beacon if adm. control is mandatory for ACs
 - New ACs/STAs must make explicit requests to the AP and
 - provide the AP with: packet size, mean data rate, min PHY rate etc
 - ▶ Based on this info a new AC is granted access with a response
 - How to make this decision is non trivial and not defined in the standard
 - The response contains the *medium time* allowed for the specific AC
 - The actual admission control algorithm is not specified in the standard

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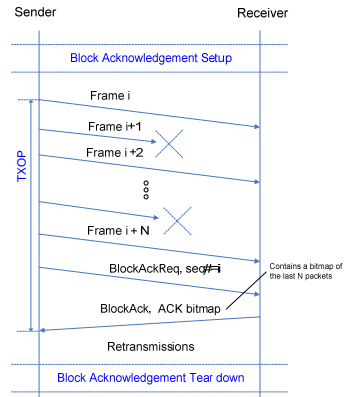
802.11e: Block Acknowledgement Mode

▶ 802.11 has inefficient ARQ

- ▶ Stop and wait, immediate ACK scheme
- ▶ Purpose is two-fold: detect lost packets, adjust CW
- ▶ Overhead is large, a significant share of the capacity is wasted

▶ Two new config. for ARQ

- ▶ No ARQ, Block Acknowledgement mode
- ▶ Block Acknowledgement mode is a type of selective repeat
- ▶ May be used in contention free bursting
- ▶ A new problem.. How to adjust CW when immediate feedback is lost?

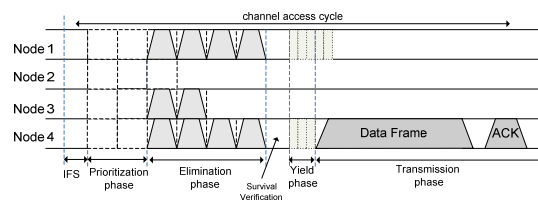


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EY-NPMA (MAC for HiperLAN 1)

▶ Elimination Yield Non-preemptive Priority Multiple Access

- ▶ MAC for HiperLAN Type 1, p2p ad-hoc mode, some QoS support, 23 Mbps



- ▶ **Prioritization phase:** nodes listen for a number of slots according to their priorities.
- ▶ **Elimination phase:** length is sampled from a *truncated geometric distribution* (max length = m), The probability of selecting a burst of length k is:

$$P(k) \stackrel{p=0.5}{=} \begin{cases} p^k(1-p) & \text{if } 0 \leq k < m \\ p^m & \text{if } k = m, \end{cases}$$

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EY-NPMA (MAC for HiperLAN 1)

▶ *The Yield phase:*

- ▶ The remaining nodes will sense the channel for a uniformly chosen number of slots
- ▶ *The winner:* selects the fewest number of mini slots and starts the transmission

▶ **Two channel access modes**

- ▶ Access in **channel free condition:**
 - listen to the channel for a random number of slots ($0, k$)
 - if idle transmit, Intended for lower channel loads
- ▶ Access in **synchronized channel condition**
 - Immediately following the previous channel access cycle
 - For higher loads

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EY-NPMA (MAC for HiperLAN 1)

▶ **Prioritization phase**

- ▶ Each node has a so-called channel access priority, P_i
- ▶ Defines h priorities, with 0 denoting the highest priority
- ▶ Priorities are **non preemptive** only nodes with highest P_i contends
- ▶ Under high loads only the highest priorities will access the channel

▶ **IEEE 802.11e priorities vs. HiperLAN priorities**

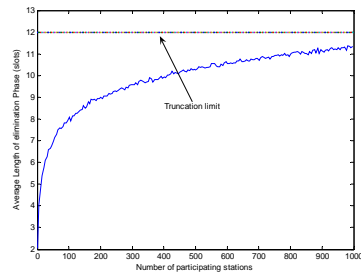
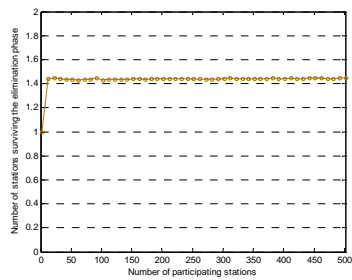
- ▶ Priorities in H1 are *non-preemptive* while *preemptive* in 802.11e
- ▶ In 802.11e backoff performed after AIFS (additional idle time)
- ▶ In HiperLAN a burst follows immediately after AIFS (Prio phase)

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EY-NPMA performance

▶ Elimination phase length

- ▶ The number of nodes have only an effect of the length of the elimination phase (right figure)



▶ Elimination phase survivors

- ▶ the number surviving this phase is almost independent on the number of participating nodes (left figure)

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EY-NPMA vs. 802.11 comparison

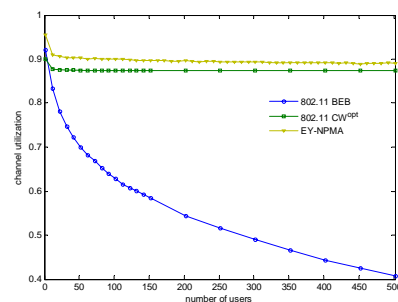
▶ Simulation study

- ▶ Simple model of the MAC layers
- ▶ Under saturation conditions
- ▶ Same PHY layer as 802.11a is assumed, i.e. slot times etc.
- ▶ All nodes have the same priorities
- ▶ No propagation effects are modeled

▶ Results from Ad hoc study

- ▶ EY-NPMA is a 'noise protocol'
- ▶ Under high loads much background noise will be generated due to the elimination phase

▶ 802.11 vs. HiperLAN Type 1



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ETSI HiperLAN Type 2

▶ **Centralized mode with AP**

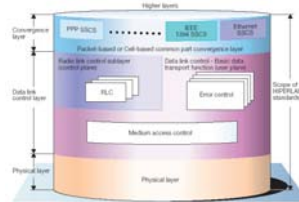
- ▶ A complex standard published in 2000 by ETSI
- ▶ Resemblance with a telecommunication std.
- ▶ An ad hoc mode but requires central control

▶ **H2 Features**

- ▶ High speed transmission, up to 54 Mbps
- ▶ Connection oriented cf. IEEE 802.11
- ▶ QoS, DFS, TPC, convergence layers
- ▶ Mobility support, Interworking with e.g. UMTS, ATM, etc.

▶ **Medium Access Control (MAC)**

- ▶ The air interface is based on TDMA: MAC frames have a fixed size and are repeated every 2ms (time slots)
- ▶ Time Division Duplex (TDD): Uplink and downlink are multiplexed onto the same MAC frame
- ▶ Many control channels are mapped onto the MAC frame



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ETSI HiperLAN Type 2

▶ **Physical layer**

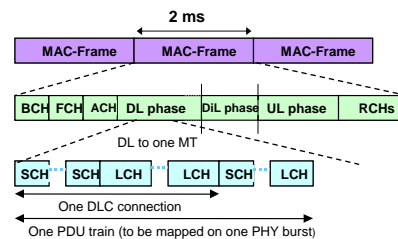
- ▶ OFDM, 52 sub carriers, 54 Mbps, 5 GHz
- ▶ Similar to 802.11a, a harmonization between the two

▶ **Transport Channels**

- ▶ **Broadcast Channel (BCH)**
Control info, reaches all MTs, for RRC functions, e.g. power levels, AP ID
- ▶ **Frame Channel (FCH)**
describes structure of current MAC frame, e.g. size of DL phase.
- ▶ **Random Access Channel (RCH)**
For MTs to request transmission resources in future frames
- ▶ **Access Feedback Channel (ACH)**
information on previous access attempts made in the RCH

▶ **Resource Control (MAC)**

- ▶ MTs make requests in RCH using slotted Aloha, exponential backoff
- ▶ centralized controller schedules the resource, polling



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