

S-72.3280

Advanced Radio Transmission Methods

Part1: Linear Receivers for interfering channels

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Introduction to ISI and equalization

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Baseband receiver

1. receiver (pulse shaping) filter
 2. sampling
 3. channel estimation in signal space
 4. Inter-symbol interference mitigation in signal space
 5. (soft) symbol detection
 6. decoder
- Here we concentrate on 4
 - understanding equalization based on matrix operations in signal space
 - as opposed to pre-sampling frequency domain & filtering treatment prevalent in literature

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Signal model in complex signal space

- ★ There are N_r received signals, \mathbf{y} is a $N_r \times 1$ vector
- ★ There are N_t transmitted symbols, \mathbf{x} is a $N_t \times 1$ vector
 - ▶ the symbols are independent, and normalized to have power 1: $E\{\mathbf{x}\mathbf{x}^H\} = \mathbf{I}$
 - ▶ The identity matrix is denoted by \mathbf{I}
- ★ The noise \mathbf{n} is additive white Gaussian, a $N_r \times 1$ vector
 - ▶ noise covariance is $E\{\mathbf{n}\mathbf{n}^H\} = N_0 \mathbf{I}$
 - ▶ noise PDF of each component : $p(n) = \frac{1}{\pi N_0} e^{-|n|^2/N_0}$
 - ▶ joint noise PDF: $p(\mathbf{n}) = \frac{1}{(\pi N_0)^{N_r}} e^{-|\mathbf{n}|^2/N_0}$ where $|\mathbf{n}|^2 = \mathbf{n}^H \mathbf{n}$
- ★ channel \mathbf{H} is a $N_r \times N_t$ matrix, includes:
 - ▶ physical channel
 - ▶ pulse shaping filtering at Tx and Rx
 - ▶ Tx power level

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Signal space example

- three received signals, two transmitted symbols:

Vector signal model

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \\ h_{31} & h_{32} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix}$$

consists of the three equations:

$$\begin{aligned} y_1 &= h_{11}x_1 + h_{12}x_2 + n_1 \\ y_2 &= h_{21}x_1 + h_{22}x_2 + n_2 \\ y_3 &= h_{31}x_1 + h_{32}x_2 + n_3 \end{aligned}$$

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Signal model II

- The task of the receiver is to estimate the transmitted symbols from this set of equations.
- Based on the same signal model receivers for a multitude of cases may be understood
 - Multiple input, multiple output channels (MIMO)
 - multiuser detection
 - equalization (ISI)

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MIMO

- ★ signal model represents reception in one symbol period
- ★ N_t transmit antennas
- ★ N_r receive antennas
- ★ h_{mn} is channel between Tx antenna n and Rx antenna m
- ★ Multiple symbols transmitted simultaneously:
 - x_n from Tx antenna n
 - ▶ intentional non-orthogonality
 - ▶ interference between simultaneously transmitted symbols

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Multiuser detection, multiple Rx antennas

- ★ signal model represents reception in one symbol period
- ★ N_t users *synchronously* transmitting on the same channel
- ★ N_r receive antennas
- ★ h_{mn} is channel between user n and Rx antenna m
- ★ Multiple symbols received simultaneously:
 - x_n from user n
 - ▶ intentional non-orthogonality (e.g. CDMA)
 - ▶ interference between users

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Multuser detection, CDMA

- ★ signal model represents reception over multiple chip periods
- ★ one spread symbol transmitted per user
- ★ N_t users *synchronously* transmitting on the same channel
- ★ N_r received chips, $N_r =$ spreading factor
- ★ h_{mn} is channel times spreading code of user n in received chip m
- ★ Multiple symbols received simultaneously: x_n from user n
 - ▶ intentional non-orthogonality
 - ▶ interference between users

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Channel convolution, ISI and equalization

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Transmitted Base band signal

- Follow path of individual symbol from transmitter, through air interface to base band receiver.

Notation:

- ★ Transmitter pulse shaping filter $f_t(t)$
- ★ Receiver (pulse shaping) filter $f_r(t)$
- ★ channel impulse response $c(t)$
- ★ symbol interval T

Transmitted base band (equivalent low-pass) signal, independent symbols transmitted with interval T using pulse shape f_t

$$x(t) = \sqrt{P} \sum_m x_m f_t(t - mT)$$

- ★ transmit power P , symbols x_m normalized to unit power
- ★ transmit (and receive) filter should have compact support - causality

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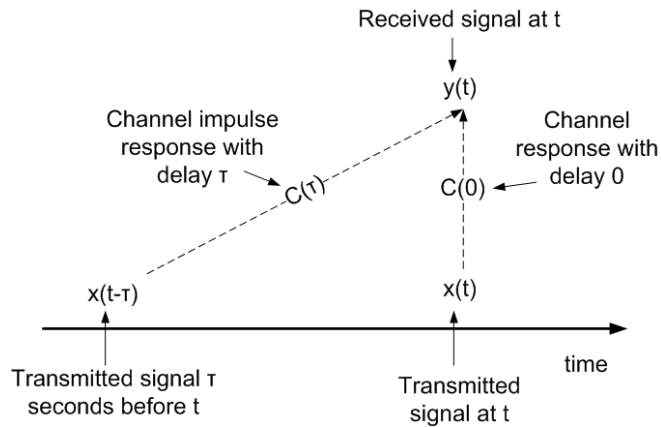
Received base band signal

$$y_b(t) = \int_{-\infty}^{\infty} d\tau x(t - \tau) c(\tau) + n(t) = (x * c)(t) + n(t)$$

- Received BB signal is a **convolution** of channel and transmitted signal
- at each time instant
 - received signal sum of multiple delayed copies of transmitted signals
 - delays caused by channel impulse response
- channel impulse response is causal
- propagation time difference absorbed into definition of $c(t)$

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Channel convolution



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AWGN process

- ★ AWGN process $n(t)$ has the auto-correlation

$$E \{n(t) n(t')^*\} = N_0 \delta(t - t')$$

- ▶ $\delta(t - t')$ is the Dirac delta-function:

$$\int_{-\infty}^{\infty} dt f(t) \delta(t - t') = f(t')$$

- ★ below, limits of integrals generally dropped

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Example: Flat fading (single-tap) channel

- ★ channel impulse response

$$c(t) = \delta(t - d)$$

- ▶ d is propagation delay between transmitter and receiver

- ★ received signal becomes

$$y_b(t) = x(t - d) + n(t)$$

- ▶ delayed copy of transmitted signal

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Receive (pulse shaping) filtered signal

- ★ received signal after filtering

$$\begin{aligned} y(t) &= \int d\tau' y_b(t - \tau') f_r(\tau') \\ &= \int d\tau \underbrace{\int d\tau' f_r(\tau') x(t - \tau' - \tau) c(\tau)}_{\text{Rx filtered Tx signal } x_r(t-\tau)} + \underbrace{\int d\tau' n(t - \tau') f_r(\tau')}_{\text{Rx filtered noise } n_r(t)} \end{aligned}$$

- ★ the part due to Rx filtered Tx signal:

$$x_r(t) = \sqrt{P} \sum_m x_m \int d\tau' f_r(\tau') f_t(t - mT - \tau') \equiv \sqrt{P} \sum_m x_m f(t - mT)$$

- ▶ convolution of the Rx and Tx filters: combined Rx-Tx pulse shaping filter

$$f(t) = (f_r * f_t)(t) = \int d\tau' f_r(\tau') f_t(t - \tau')$$

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Receive (pulse shaping) filtered signal II

- ★ The received signal after pulse shaping is

$$y(t) = \sum_m x_m \sqrt{P} \int d\tau f(t-mT-\tau) c(\tau) + n_r(t) \equiv \sum_m x_m h(t-mT) + n_r(t)$$

- ★ convolution of channel impulse response and combined Tx-Rx pulse shaping filters is

$$h(t) = \sqrt{P} (f_t * f_r * c)(t) = \sqrt{P} \int d\tau \int d\tau' f_t(t-\tau-\tau') f_r(\tau') c(\tau)$$

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Sampling

- ★ After Rx filtering, signal is sampled:

$$\begin{aligned} y_k &= y(kT' + \Delta) = \sum_m x_m h(kT' - mT + \Delta) + n_r(kT' + \Delta) \\ &= \sum_m h_{km} x_m + n_k \end{aligned}$$

- ★ sampling interval $T' \leq T$
 - ▶ symbol-spaced Tapped Delay Line: $T' = T$
 - ▶ fractionally spaced TDL: $T' < T$
- ★ sampling instances $kT' + \Delta$,
 - ▶ Δ reflects the insecurity in timing
- ★ channel coefficients h_{km}
- ★ noise samples n_k

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Symbol-spaced sampling

- ★ One received sample per transmitted symbol

$$y_k = h_{kk} x_k + \underbrace{\sum_{m \neq k} h_{km} x_m}_{\text{ISI}} + n_k$$

- ★ if $h_{km} \neq h\delta_{km}$, there is Inter-Symbol-Interference (ISI)
- ★ With symbol-spaced sampling, the channel taps are

$$h_{km} = \sqrt{P} \int d\tau f((k-m)T + \Delta - \tau) c(\tau)$$

- ★ In flat fading $h_{km} = \sqrt{P} f((k-m)T + \Delta - d)$
- ★ Nyquist criterion: $f((k-m)T + \Delta - d) = \delta_{km}$

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Tx-Rx filter design

- The combined Tx & Rx filters should be designed to minimize ISI
- The Tx filter should be designed to optimize bandwidth usage
- If f_t is rectangular pulse, there is no ISI
 - ⇒ extensive out-of band emissions at Tx
 - ⇒ pulse shaping at Tx is required
- family of pulse shapes f satisfying Nyquist criterion: Raised Cosine pulses

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Raised Cosine pulse shaping

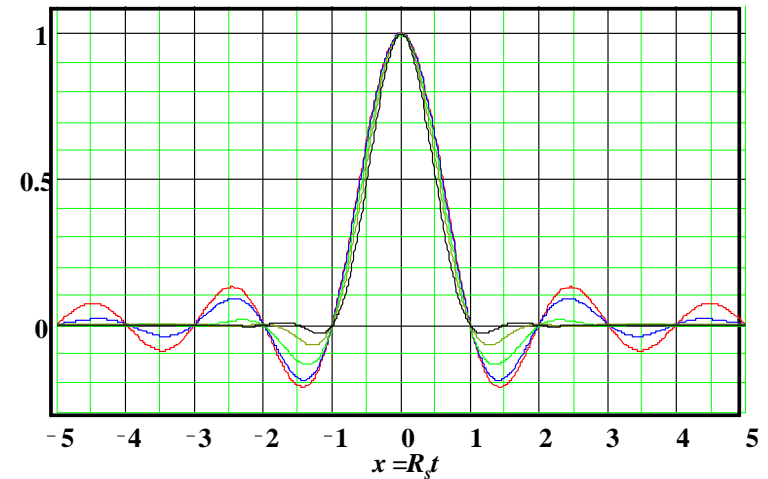
$$f_{\text{RC}}(t) = \frac{\sin(\pi t/T)}{\pi t/T} \cdot \frac{\cos(\alpha \pi t/T)}{1 - (2\pi t/T)^2}$$

- ★ If f is a Raised Cosine pulse, and $\Delta = d$
 - ▶ no ISI
 - ▶ $h_{km} = \sqrt{P} \delta_{km}$.
- ★ vulnerability to sampling inaccuracy
- ★ When non roll-off ($\alpha = 0$) f is sinc-pulse
 - ▶ ISI with non-exact timing infinite
- ★ With roll-off ($\alpha > 0$),
 - ▶ RC tolerates some timing inaccuracy (“eye open”).

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Raised cosine pulse

Raised cosine filter impulse responses: $\alpha = 0, 0.25, 0.5, 0.75, 1$



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Root-Raised Cosine (RRC)

- ★ noise power at Rx is minimized if f distributed evenly between Tx and Rx: root-raised cosine

$$f_t = f_r = f_{\text{RRC}}$$

$$f_{\text{RRC}} = \frac{\sqrt{1/T}}{1 - (4\alpha t/T)^2} \left(\frac{\sin(\pi(1-\alpha)t/T)}{\pi t/T} + \frac{4\alpha}{\pi} \cos(\pi(1+\alpha)t/T) \right)$$

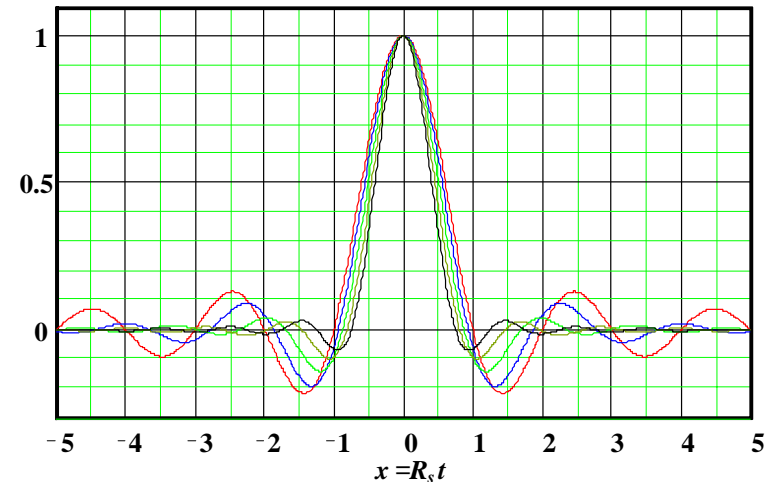
$$f_{\text{RRC}} * f_{\text{RRC}} = f_{\text{RC}}$$

- RRCs with delay kT are orthogonal functions
- with RRC at Tx & Rx
 - matched filter:
 - receiver matched to orthogonal Tx waveform
 - no noise colouring (see two slides ahead)

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RRC pulse

Root raised cosine filter impulse responses: $\alpha = 0, 0.25, 0.5, 0.75, 1$



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Noise sample covariance

- ★ sampled, Rx-filtered noise process

$$n_k = n_r(kT + \Delta) = (n * f_r)(kT + \Delta)$$

- ★ noise covariance

$$\begin{aligned} E\{n_m n_k^*\} &= \int d\tau \int d\tau' f_r(\tau) f_r(\tau') \underbrace{E\{n(mT + \Delta - \tau) n^*(kT + \Delta - \tau')\}}_{=N_0 \delta((m-k)T)} \\ &= N_0 (f_r * f_r^*)((m-k)T) \end{aligned}$$

- ★ If f_r is RRC, we have

$$E\{n_m n_k^*\} = N_0 \delta_{mk}$$

- RRC filtering at Rx does not color the noise

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Optimal filtering in flat fading

- In frequency flat channel, RRC filtering at Tx and Rx is optimum
 - removes ISI
 - maximizes SNR at the output of the sampler
 - does not color noise
 - consequence of RRC orthogonality
- If some other Rx filter is used, one may have to whiten the noise before further processing.

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Frequency selective channel

- In frequency selective fading, Rx-filtering with possible noise whitening is done before sampling
- If Rx-filter is RRC, noise samples are uncorrelated, and base band detector may operate directly on them
- Combined Tx-Rx still best to be RC, so that the filters do not needlessly increase ISI
- Filtering w.r.t. to the channel impulse response may be done before sampling, or after sampling in signal space
- In latter case, the channel taps h_{km} estimated in signal space
 - h_{km} includes channel and filter impulse responses
- Equalization of ISI done on the samples in signal space

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Fractional spaced sampling

- Symbol-spaced sampling works when the receiver knows the sampling time perfectly.
- If imperfect or random sampling timing
 - oversampling (at least Nyquist rate) required to fully be able to reproduce the band-limited signal.
 - the additional samples of Nyquist sampling compared to symbol-spaced sampling can be understood to be required to estimate transmitter pulse timing
- receivers for oversampled signals: fractional spaced equalizers
 - not discussed here

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Signal model for Equalization

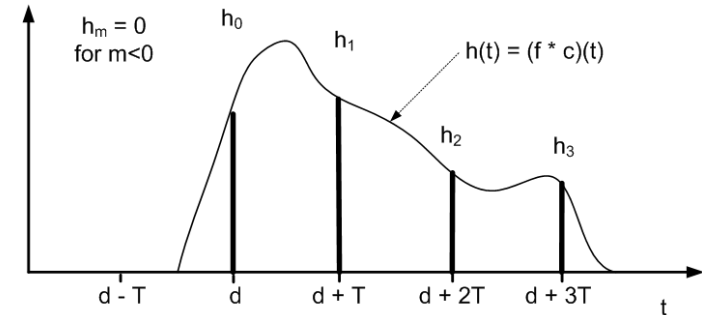
- ★ In signal model after sampling assume that
 - ▶ channel taps are constant $h_{km} = h_{k-m}$
 - ▶ causality realized as $h_m = 0$ for $m < 0$
 - ▶ there are L non-zero channel taps $\{h_m\}_{m=0}^{L-1}$
- ★ we have

$$y_k = h_0 x_k + \sum_{m=1}^{L-1} h_m x_{k-m} + n_k$$

where n_k is AWGN.

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Tapped Delay Line



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Signal model for Equalization: finite block

- ★ For finite block of N_t symbols, this can be written in the vector form

$$\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{n}$$

where the channel matrix is a Toeplitz matrix.

- ★ Example: block of $N_t = 5$ Rx symbols, $L = 3$ channel taps

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix} = \begin{bmatrix} h_2 & h_1 & h_0 & 0 & 0 & 0 & 0 \\ 0 & h_2 & h_1 & h_0 & 0 & 0 & 0 \\ 0 & 0 & h_2 & h_1 & h_0 & 0 & 0 \\ 0 & 0 & 0 & h_2 & h_1 & h_0 & 0 \\ 0 & 0 & 0 & 0 & h_2 & h_1 & h_0 \end{bmatrix} \begin{bmatrix} x_{-1} \\ x_0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_2 \\ n_3 \\ n_4 \\ n_5 \end{bmatrix}$$

- ★ E.g.: $y_5 = h_0x_5 + \underbrace{h_1x_4 + h_2x_3}_{\text{ISI}} + n_5$

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Signal model for Channel Equalization

- ★ signal model represents reception of sequence of symbol periods
- ★ N_t symbols in a transmission block that is equalized
- ★ N_r samples at the receiver
- ★ h_{mn} is channel between transmitted symbol n and received sample m
- ★ Multiple symbols received simultaneously: x_n from user n
 - ▶ non-orthogonality caused by the channel (and possibly filters)
 - ▶ inter-symbol interference

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