

## MAP algorithm for a punctured code

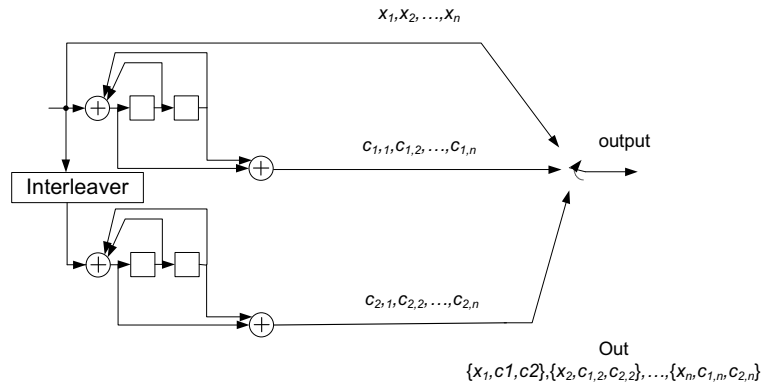


Figure: Non punctured encoder

## MAP algorithm for a punctured code

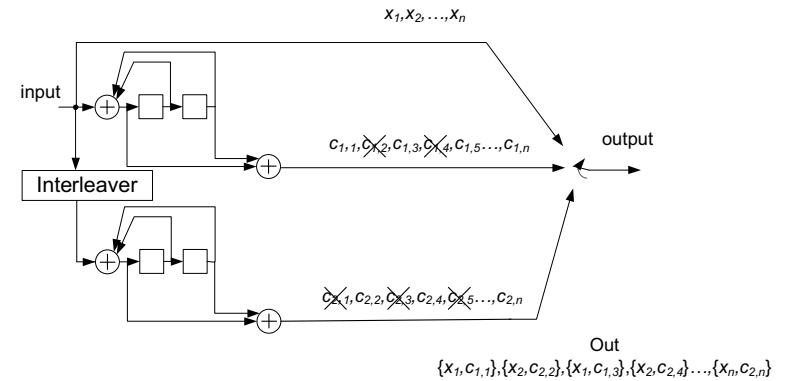


Figure: Punctured encoder

## MAP trellis for a punctured code

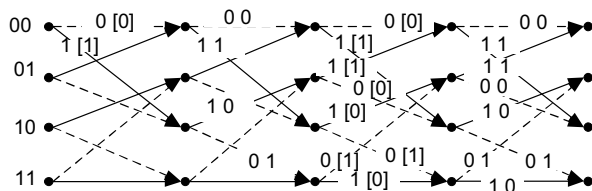


Figure: Punctured MAP for decoder 1

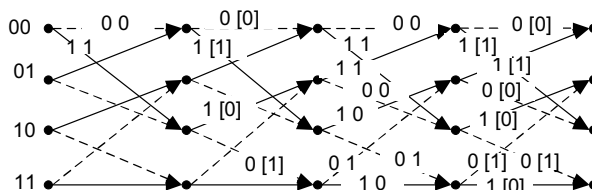


Figure: Punctured MAP for decoder 2

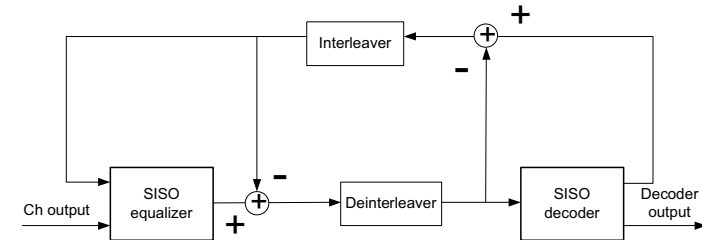
## Turbo equalization

- Making the equalization based only on the channel knowledge and observed values is suboptimal
- The equalization does not utilize the knowledge about the code structure
- Multipath channel can be interpreted as a spreading code
  - The spreading code can be described by a trellis structure
  - The ML equalizer on this trellis is the Viterbi algorithm
  - For one bit the optimal algorithm is marginalization by APP calculation
- Together the channel and the error correction code give a serially concatenated code
  - Serially concatenated codes can be decoded by applying turbo processing
- Turbo equalizer is an iterative equalization/decoding process

## Soft equalizer

- For turbo equalization the equalization operation should
  - provide a soft values to the decoding block
  - be able to incorporate a priori values from the channel code decoder block to the equalization operation
- Soft trellis based equalizer
  - APP equalizer
  - SOVA
- Soft interference cancellation
  - Soft DFE
  - Soft sphere decoder

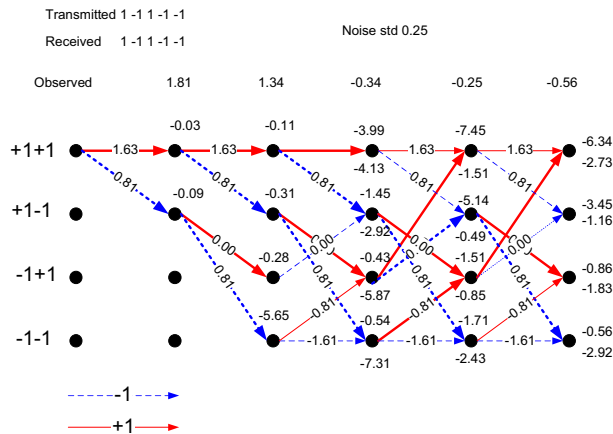
## Turbo Equalizer



Turbo Equalizer [Douillard et al. 1995]

SISO: MAP, Log-MAP, Max-Log-MAP, SOVA, Soft DFE

## Example

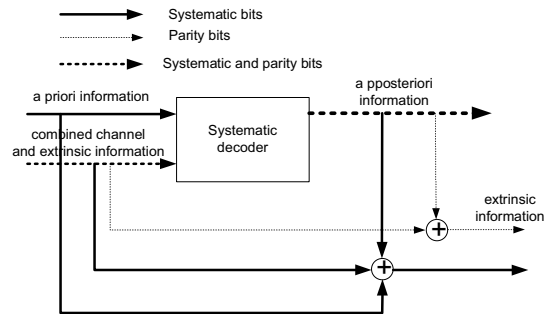


Trellis for the 3-path symbol spaced channel [0.407 0.815 0.407]

## How to make an APP equalizer

- For turbo decoding purposes we have to change the normal equalizer to an equalizer with Soft Input Soft Output.
- For creating the soft output we can use a soft trellis decoding
- For accepting soft input we have to consider that
  - The bit impacts multiple stages in the trellis.
  - Question: At which stage to combine the prior knowledge?
  - It turns out that the prior information can be incorporated at whatever stage where this particular input bit is present in the trellis

## Information flow for a soft equalizer



- A-priori (intrinsic) - information, known before decoding (equalisation), from other sources than received sequence or code constraints
- Extrinsic - information provided by decoder(equaliser), based on the received sequence and a-priori information of other bits
- A-posteriori - information generated by a SISO algorithm

## Making MAP equalizer to Soft In equalizer

- In a stage  $k$  the edge metric is calculated based on the bits in the stage channel bit and channel coefficients

$$\prod_k p(y_k | x_k, s_k, h_{ch}) = \sum_k (y_k - f(x_k, s_k, h_{ch}))^2$$

Where

$$f(x_k, s_k, h_{ch}) = h_1 \cdot x_k + h_2 \cdot x_{k-1} + \dots + h_L \cdot x_{k-(L-1)}$$

- For given extrinsic information we weight this metrics with the symbol probability

$$\sum_k (y_k - f(x_k, s_k, h_{ch}))^2 \cdot p(x_k = X)$$

where  $X$  is the symbol value corresponding to the particular edge in the trellis

## Adaptive MLSE Equalizer

With the LMS algorithm the tap coefficients are updated

$$\hat{h}_i(k+1) = \hat{h}_i(k) + \alpha \epsilon_{k-Q} \hat{x}_{k-i-Q}$$

where  $\alpha$  is the adaptation state size,  $Q$  is the decision delay,  $Q > 5L$  for minimal performance degradatation, and error at epoch  $k - Q$  is

$$\epsilon_{k-Q} = y_{k-Q} - \sum_{i=0}^L \hat{h}_i(k) \hat{x}_{k-i-Q}$$

Channel variations over  $Q$  degrade the tracking performance

Reducing  $Q$  reduce reliability of  $\hat{x}_{k-i-Q}$

Solution - per-survivor processing

$$\hat{h}_i(k+1) = \hat{h}_i(k) + \alpha \epsilon_k \tilde{x}_{k-i}$$

where  $\tilde{x}$  is the surviving sequence for a state.

Each state uses individual channel estimator.

## Soft Feedback Equalizer

- In order to reduce the complexity of MLSE equalizer we can reduce the number of states.
- Alternatively if the bits are known we can compensate the ISI from the neighbouring bits.
- If the bits are partly known we can compensate the interference partially.
- The amount knowledge about a bit can be expressed as a **soft bit**.
  - For a binary symbol the soft bit is a MMSE estimate of the bit.
- The equalization is made by substracting interference described by the soft bit and scaled by the corresponding channel tap.

## System model

- We assume that at the front end the channel matched filter is applied.
  - The corresponding channel response  $h_l$  becomes symmetric with maximum at the center.
  - The length of such channel response is  $2L - 1$ , where  $L$  corresponds to the amount of channel taps.

The received signal is modeled at the output of the matched filter

$$y_k = \sum_{l=-(L-1)}^{L-1} h_l x_{k-l} + n_k$$

Where  $x$  corresponds to the transmitted symbol

$n$  is the additive Gaussian noise

$y_k$  is the received symbol at the moment  $k$

## Probability of the bit

The probability of a particular bit in a multipath channel depends on the neighbouring symbol values and on the channel tap values. For one symbol  $k$  we have

$$\begin{aligned} \log P(y_1, \dots, y_K | x_1, \dots, x_K) &= \\ &= \log P(y_k | x_k, \dots, x_{k-(L-1)}) + \log P(y_1, \dots, y_{k-1}, y_{k+1}, \dots, y_K | x_1, \dots, x_k) \end{aligned}$$

The second part in this equation describes the state probability at the stage  $k$  and the first part in this equation impacts the transition in the trellis section  $k$ .

We can calculate probability of each symbol separately.

$$\begin{aligned} \log P(y_k, \dots, y_1 | x_K, \dots, x_1) &= \\ &= \sum_{k=1}^K \ln P(y_k | x_1, \dots, x_K) \approx \sum_{k=1}^K \log P(y_k | x_{k-(L-1)}, \dots, x_{k+(L-1)}) \end{aligned}$$

In Gaussian channel the approximated symbol probability is

$$p(y_k | x_{k+L-1}, \dots, x_{k-(L-1)}) = \frac{1}{\sqrt{2\pi}\sigma_n} \exp \left( -\frac{\left( y_k - \sum_{l=-(L-1)}^{L-1} h_l x_{k-l} \right)^2}{2\sigma_n^2} \right) \prod_{l=-(L-1)}^{L-1} p(x_l)$$

Difference compared to the full trellis based calculation is that we consider only one trellis section.

The previous state is defined by the symbol sequence

$$x_{k-(L-1)} \dots x_{k-1}$$

The next state is defined by the symbol sequence  $x_{k+1} \dots x_{k+(L-1)}$

If we know these bit probabilities we can calculate the states probabilities.

For example for a state  $[0 \ 0]$

$$p \{ x_{k-1} = 0, x_{k-2} = 0 \} = p \{ x_{k-1} = 0 \} p \{ x_{k-2} = 0 \}$$

Here we assumed that the symbols  $x$  are independent.



## SDF equalization algorithm

1. Based on the  $llr$  from the decoder output calculate the soft bit values.  
in first iteration  $llr = 0$
2. Subtract the interfering soft bits from the received symbol value  
This operation reduces ISI.
3. Calculate the probability for the bit value.

## Calculation of output soft value

- The soft equalizer output should provide soft values to the next decoding operation.
- The soft equalized bit values contain remaining interference and noise.
  - We approximate this by Gaussian distribution.
- For calculating the output soft value we need the variance and mean of the output value.

The noisy value of  $y_k^i$

$$y_k^i = h_0 x_k + \sum_{\substack{l=-(L-1) \\ l \neq 0}}^{L-1} h_l (x_{k-l} - \hat{x}_{k-l}) + n$$

### Estimation of the mean of $\hat{y}^i$

Mean of  $y_k^i$  is  $h_0 \cdot x_k$ , since  $x_{k-1} \in \{\pm 1\}$  the amplitude of the symbol is  $h_0$ .

### Estimation of the variance

By assuming that all the bits are independent the variances of the terms

$$h_l (x_{k-l} - \hat{x}_{k-l})$$

can be evaluated independently.

Total variance is the sum of the remaining interference variances

$$\hat{\sigma}^2 = \sigma_n^2 + \sum_{\substack{l=-(L-1) \\ l \neq 0}}^{L-1} h_l^2 (1 - \hat{x}_{k-l}^2)$$

